Convergence guarantees for gradient descent methods in optimization for non-convex function approximation (distributed neural network training)

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Previous semester

- *Massively distributed*. The number of mobile device owners is massively bigger than average of the number of training samples on each device.
- Unbalanced. Some users produce significantly more data than others.
- Non-IID. The data generated by each user are quite different.



Figure. Top-1 validation accuracy for IMAGE CLASSIFICATION over the CIFAR-10 dataset.

Let us consider the *C*-class classification problem. Let  $f : X \to S = \{z | \sum_{i=1}^{C} z_i = 1, z_i \ge 0 \ \forall i \in [C]\}$  denote the prediction function and  $f_i$  predicts the probability that the sample belongs to the *i*-th class.

The learning problem is to solve the following optimization problem:

$$\min_{w} L(w) = \min_{w} \mathbb{E}_{x, y \sim p} \left[ \sum_{i=1}^{C} \mathbb{1}_{y=i} \log f_i(x, w) \right]$$
$$= \min_{w} \sum_{i=1}^{C} p(y=i) \mathbb{E}_{x|y=i}[\log f_i(x, w)]$$

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Weight updates at centralized setting:

$$w_t^{(c)} = w_{t-1}^{(c)} - \eta \sum_{i=1}^{C} p(y=i) \nabla_w \mathbb{E}_{x|y=i}[\log f_i(x, w_{t-1}^{(c)})]$$

Weight updates at the k-th client

$$w_t^{(k)} = w_{t-1}^{(k)} - \eta \sum_{i=1}^{C} p^{(k)}(y=i) \nabla_w \mathbb{E}_{x|y=i}[\log f_i(x, w_{t-1}^{(k)})]$$

The m-th synchronization (assume synchronization is conducted every T steps)

$$w_{mT}^{(f)} = \sum_{k=1}^{K} \frac{n^{(k)}}{\sum_{k=1}^{K} n^{(k)}} w_{mT}^{(k)}$$

 $n^{(k)}$  denote the amount of data and  $p^{(k)}$  denote the data distribution on client k.



Figure. Ilustration of the weight divergence for federated learning with-IID and non-IID data.

$$\begin{split} ||\boldsymbol{w}_{mT}^{(f)} - \boldsymbol{w}_{mT}^{(c)}|| &\leq \sum_{k=1}^{K} \frac{n^{(k)}}{\sum_{k=1}^{K} n^{(k)}} (a^{(k)})^{T} ||\boldsymbol{w}_{(m-1)T}^{(f)} - \boldsymbol{w}_{(m-1)T}^{(c)}|| \\ &+ \eta \sum_{k=1}^{K} \frac{n^{(k)}}{\sum_{k=1}^{K} n^{(k)}} \sum_{i=1}^{C} ||p^{(k)}(y=i) - p(y=i)|| \sum_{j=1}^{T-1} (a^{(k)})^{j} g_{max}(\boldsymbol{w}_{mT-1-k}^{(c)}), \end{split}$$

where  $g_{max}(w) = \max_{i=1}^{C} ||\nabla_w \mathbb{E}_{x|y=i} \log f_i(x, w)||$  and  $a^{(k)} = 1 + \eta \sum_{i=1}^{C} p^{(k)}(y=i) \lambda_{x|y=i}$ .

# Convex optimization of FedAvg on Non-IID Data (X.Li, K.Huang, W.Yang, S.Wang and Z.Zhang, 2020)

## Assumptions

- *L* Lipschitz gradient: $\|\nabla f_i(u) \nabla f_i(v)\| \le L \|u v\|$
- $\mu$  strongly convex:  $f_i(u) \ge f_i(v) + (u-v)^T \nabla f_i(v) + \frac{\mu}{2} ||u-v||^2$
- Bounded variance:

$$\mathbb{E}_{\xi_k \sim D_i} \left[ \|\nabla F(w, \xi_k) - \nabla f_k(w)\|^2 \right] \leq \sigma^2, \ \forall k, w$$

Bounded gradient:

$$\mathbb{E}_{\xi_k \sim D_i}\left[ \| 
abla F(w, \xi_k) \|^2 
ight] \leq G^2, \; orall k, w$$

**Main aim :** Give an analysis whether it is possible to give convergence guarantees (non-convex) in case the data over each devices is non-iid.

## Ideal 1: Splitting the loss function into convex terms and non-convex terms.

$$\min_{x\in C} f(x) = \min_{x\in C} \{g(x) - h(x)\}$$

## Assumptions

- f is bounded below C
- h is continuous and convex
- g is continuous differentiable and M<sub>g</sub> smooth

**Algorithm 1:** Subgradient-type method.

Initialization. Choose  $x_0 \in \int (C)$ , level set of  $x_0$  is in *C*. for each round  $k = 1, 2, \dots, T$  do Update:  $x_{k+1} = x_k - \alpha(\nabla g(x_k) - u_k)$  where  $u_k$  is chosen randomly from  $\partial h(x_k)$  and learning rate  $\alpha \in [0, 1/M_g]$ . end

#### Theorem

 $f(x_k)$  is strictly decreasing and converges. The limit point of  $x_k$  is also a critical point of f. Moreover, for all k,

$$Avg\left(\|
abla f(x_k)\|_2^2
ight) \leq rac{2(f(x_0) - f(x*))}{(k+1)}$$

Ideal 2: Using local smoothness and maximal nondegeneracy

$$f(\theta) = \mathbb{E}[F(\theta, X)]$$

## Assumptions

- M is locally smooth ( there exists an open set U ⊆ ℝ<sup>d</sup> such that M ∩ U is a non-empty Ψ-dimensional C<sup>1</sup>-submanifold of ℝ<sup>d</sup>).
- f is locally three times continous differentiable on the local set of M. And the Hessian matrix of f is maximally non degenerate. (rank Hess (f)(θ) = d − Ψ = codim(M ∩ U))

**Algorithm.** Initialization: The initial data was sample from the bounded open set  $A \subseteq \mathbb{R}^d$  that contains at least one element in local set of  $\mathcal{M}$ . Denote by  $\theta_0^{k,M,r}: \Omega \to \mathbb{R}^d$  indicates k-th sample in the sampling set of size K, mini-batch size M, and parameter r > 0 involving to learning parameter. The initial data is uniformly distributed on A. i.i.d and independent from  $X_{k,m,n}$ .

Weights update: We compute independent solutions to SGD in the way

$$\theta_n^{k,M,r} = \theta_{n-1}^{k,M,r} - \frac{r}{n^{\rho}M} \left[ \sum_{i=1}^m \nabla_{\theta} F(\theta_{n-1}^{k,M,r}, X_{k,n,m}) \right]$$

Mini-batch approximation:  $F^{K,\mathfrak{M},n}: \mathbb{R}^d \times \Omega \to \mathbb{R}$  is approximated as

$$F^{\mathcal{K},\mathfrak{M},n}(\theta,w) = \frac{1}{\mathfrak{M}} \sum_{i=1}^{\mathfrak{M}} F(\theta, X_{1,n+1,m}(w))$$

After that, we identify the value that minimizes  $F^{K,\mathfrak{M},n}$  in the sense that we compute a random variable  $\theta_n^{K,M,\mathfrak{M},r}: \Omega \to \mathbb{R}^d$  which satisfies that

$$\sum_{m=1}^{\mathfrak{M}} F\left(\theta_{n}^{K,M,\mathfrak{M},r}, X_{1,n+1,m}\right) = \min_{k \in [K]} \left[\sum_{m=1}^{\mathfrak{M}} F\left(\theta_{n}^{k,M,r}, X_{1,n+1,m}\right)\right]$$

## Theorem

After running the above algorithm with  $p \in (2/3; 1)$ . There exist  $\tau, c > 0$ ,  $\kappa \in (0, 1)$  such that for every  $n, k, M, \mathfrak{M}, r \in (0, \tau)$ ,  $\epsilon \in (0, 1)$  we get

$$\mathbb{P}\left(\text{ Distance between} f\left(\theta_{n}^{k,M,\mathfrak{M},r}\right) \text{ and minima bigger than } \epsilon\right)$$
$$= \mathbb{P}\left(f\left(\theta_{n}^{k,M,\mathfrak{M},r}\right) - \inf_{\theta} f\left(\theta\right) \ge \epsilon\right) \le \frac{cK}{\epsilon^{2}\mathfrak{M}} + \left[\kappa + c\left(\frac{1}{\epsilon^{2}n^{\rho}} + \frac{n^{1-\rho}}{\sqrt{M}}\right)\right]^{K}$$

## Non-convex optimization on gradient-based methods

## Ideal 3: Using extrapolation Problem

$$\min_{x \in \mathbb{R}^d} f(x) = \min_{x \in \mathbb{R}^d} \mathbb{E} \left[ f\left(x, \xi\right) \right]$$

## Assumptions

- f(x) is L-smooth.
- There exist Δ such that f(x) − f(x<sub>\*</sub>) ≤ Δ for all x ∈ ℝ<sup>d</sup> where x<sub>\*</sub> be the global minimum of f(x).
- $f(x,\xi)$  is differentiable.
- (Bounded variance)  $\mathbb{E}\left[\|\nabla F(x,\xi) \nabla f(x)\|^2\right] \leq G^2, \ \forall x, \xi$

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## Algorithm 2: Stagewise SGDE

Algorithm StagewiseSGDE()

1 Initialization. 
$$x^0 = x_0$$
  
2 for  $s = 1, \dots, S$  do  
 $\left| \begin{array}{c} f_s(x) = f(x) + \frac{1}{2\gamma} \| x - x^{s-1} \|^2 \\ x^s = \text{SGDE}(x^{s-1}, f_s, \eta_s, T_s) \\ \text{end} \end{array} \right|$   
3 return  $x_\tau$  where  $\tau$  is chosen from  $1, \dots, S$  with probability  
 $\mathbb{P}(\tau = i) = \frac{w_i}{\sum_{j=1}^s w_s}$   
Procedure SGDE $(x_0, f, \eta, T)$   
1 Initialization.  $z_0 = x_0; g_0 = \nabla f(x_0, \xi_0)$   
2 for each round  $t = 1, 2, \dots, T$  do  
 $\left| \begin{array}{c} x_t = z_{t-1} - \eta g_{t-1} \\ g_t = \nabla f(x_t, \xi_t) \\ z_t = z_{t-1} - \eta g_t \\ \text{end} \end{array} \right|$   
3 return  $\hat{x}_t = \frac{1}{T} \sum_{t=1}^T x_t$ 

### Theorem

After running Stagewise SGDE with  $\gamma = 1/4L$ ;  $w_s = s^{\alpha}$  ( $\alpha > 1$ ) and choosing the learning parameter and the number of iteration at s-stage as follow:  $\eta_s = \frac{c\gamma}{3s} \leq \frac{1}{2L}\frac{\gamma}{3}$  and  $T_s = \frac{36s}{c}$ , we got the estimation:

$$\mathbb{E}\left[\left\|\nabla f(x_{\tau})\right\|^{2}\right] \leq \frac{20\Delta(\alpha+1)}{\gamma(S+1)} + \frac{480G^{2}c(\alpha+1)}{S+1} - \frac{60\sum_{s=1}^{S+1}w_{s}D_{T_{s}}}{\gamma\sum_{s=1}^{S+1}w_{s}}$$
where  $D_{T_{s}} = \frac{1}{16T_{s}\eta_{s}}\sum_{t=1}^{T_{s}}\|x_{t} - x_{t-1}\|^{2}$ . If we expect  
 $\mathbb{E}\left[\left\|\nabla f(x_{\tau})\right\|^{2}\right] \leq \epsilon^{2}$ , the number of stage should be  $O(1/\epsilon^{2})$ .

## Idea Traditional loss function:

$$L(w) = \frac{1}{K} \sum_{i=1}^{K} f_i(w)$$

New loss function:

$$L(w) = \frac{1}{K} \sum_{i=1}^{K} \min_{\theta_i \in \mathbb{R}^n} \{f_i(\theta_i) + \frac{\lambda}{2} \|\theta_i - w\|^2\}$$

Algorithm 3: Ongoing algorithms

**Server executes:** Initialization  $w_0$ : for each round  $t = 1, 2, \cdots$  do for each client  $k \in S_t$  do  $w_{t+1}^k \leftarrow \text{ClientUpdate}(k, w_t);$ end  $w_{t+1} \leftarrow \sum_{k=1}^{K} \frac{n_k}{n} w_{t+1}^k;$ end ClientUpdate: for  $i = 1, \dots, N$  do  $w_{i0}^t = w_t$ for  $r = 1, \cdots, R$  do  $\hat{\theta}(w_{i,r}^t) = prox_{f_i/\lambda}(w_{i,r}^t)$  $w_{i,r+1}^t \leftarrow w_{i,r} - \eta \lambda (w_{i,t}^t - \hat{\theta}(w_{i,r}^t))$ end

end

## THANK YOU FOR YOUR ATTENTION!