



APPLICATION OF SIGNATURES FOR FORECASTING

BAT-ERDENE EGSHIGLEN

SUPERVISOR : TIKOSI KINGA

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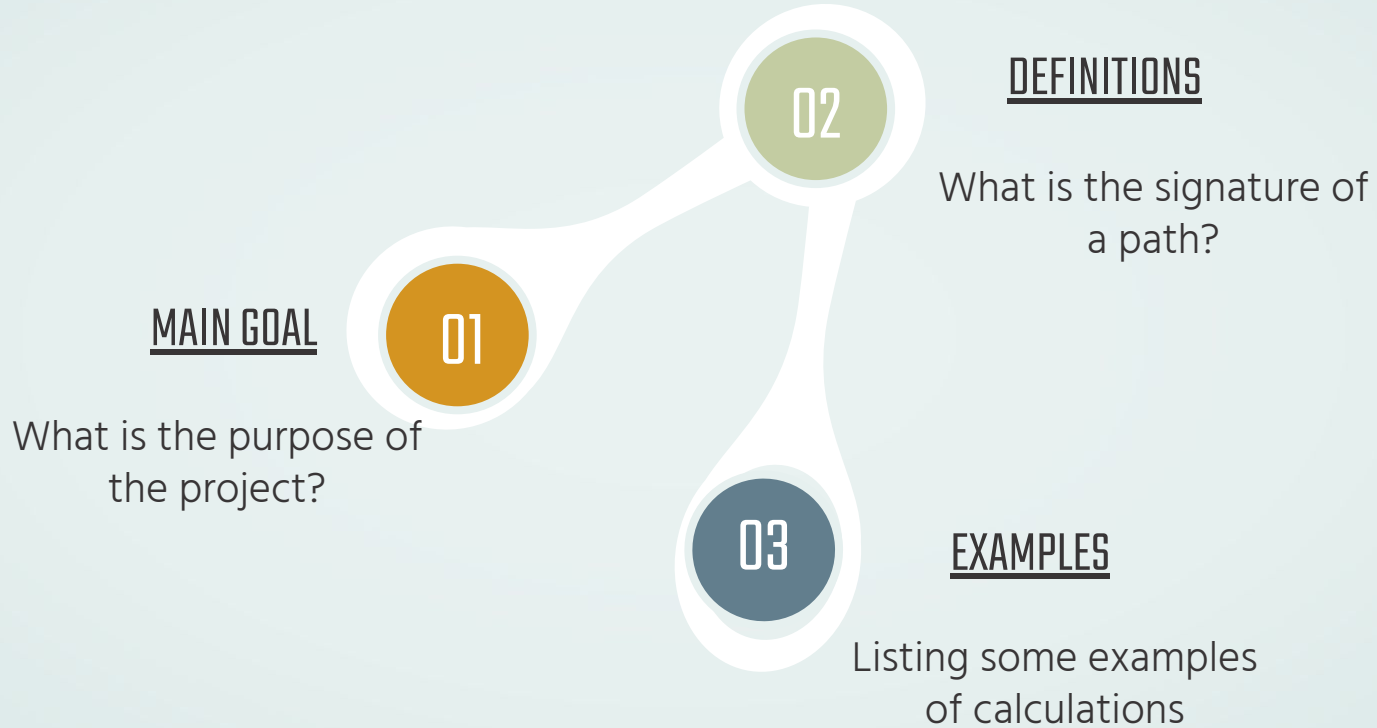
PURPOSE OF PROJECT

- UNDERSTANDING SIGNATURE AND TO USE IT ON SIMPLE SMOOTH DETERMINISTIC FUNCTIONS
- TRY TO USE IT FOR FORECASTING A CHOSEN TIME SERIES



FIRST SEMESTER

TABLE OF CONTENTS



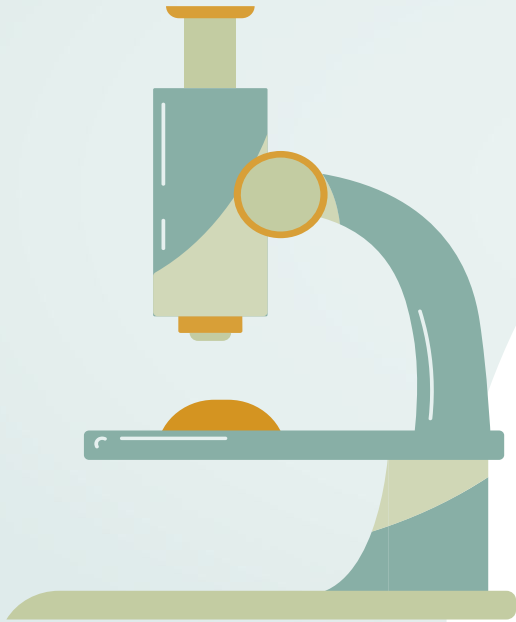
PATH

We denote a path $([a,b] \Rightarrow \mathbb{R}^m)$ by \mathbf{X} or \mathbf{X}_t parameterized by t , which belongs to $[a,b]$ coordinate paths :

$$\mathbf{X}_t = (\mathbf{X}_t^1, \mathbf{X}_t^2, \mathbf{X}_t^3, \dots, \mathbf{X}_t^m)$$

X_t^i are coordinate paths.

SIGNATURE OF A PATH



$$S(X)_{a,b} = (1, S(X)^1_{a,b'}, S(X)^2_{a,b'} \dots, S(X)^{1,1}_{a,b'} \dots)$$

1 multi index

$$S(X)_{a,t}^i = \int_{a < s < b} dX_s^i = X_t^i - X_0^i$$



$$S(X)_{a,t}^{i,j} = \int_{a < s < b} S(X)_{a,s}^i dX_s^j = \int_{a < r < s < t} dX_r^i dX_s^j$$



EXAMPLE



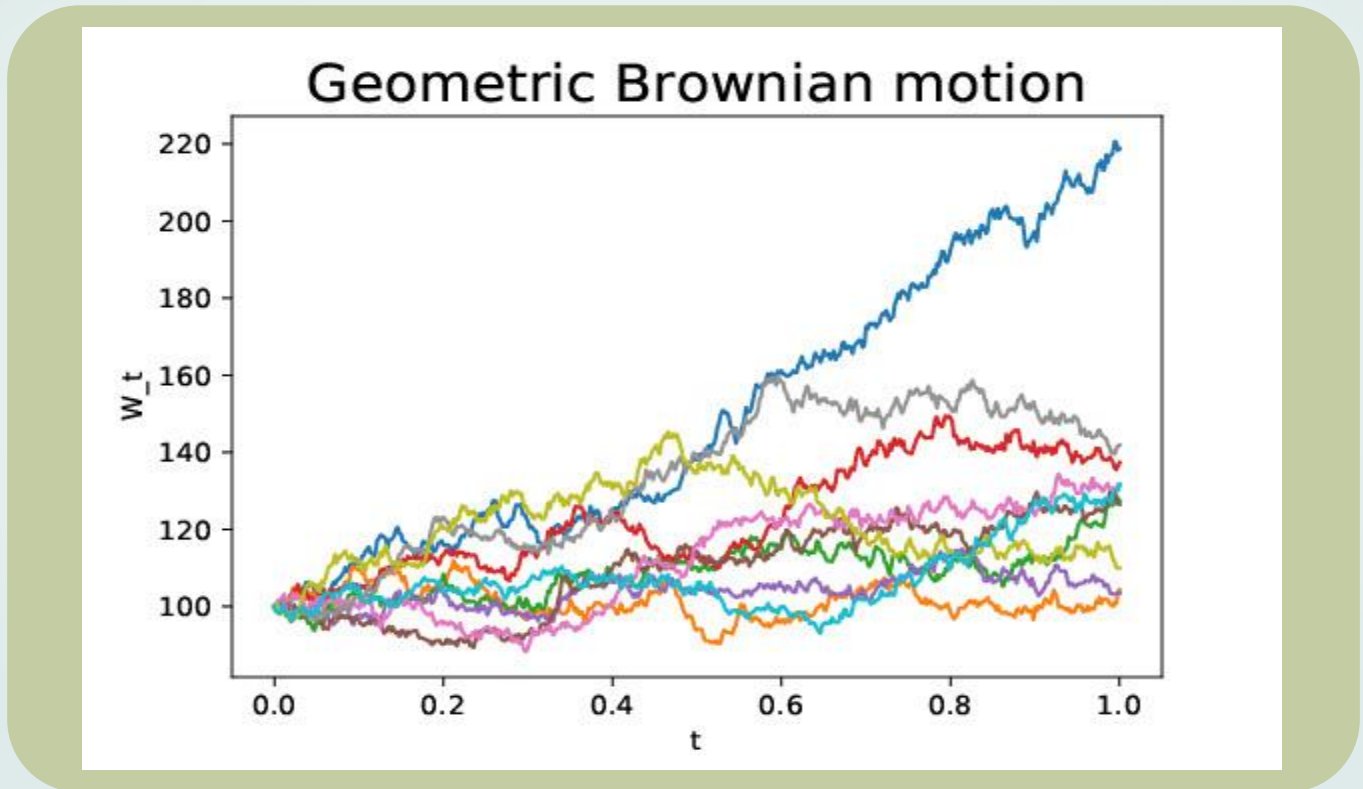
$$X_t = \{X_t^1, X_t^2\} = \{5+t^2, (t^2+1)^2\},$$

$$a=1, b=5$$

so the derivatives are

$$dX_t = \{dX_t^1, dX_t^2\} = \{2t dt, 2(t^2+1)*2t dt\},$$

PICTURE OF A ROUGH PATH





PLAN



01



02



03

Understand and use signatures on rough non-smooth paths

THANK YOU

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