

Hoist scheduling problem

Gergely Márton Szathmári

Supervisor: Markó Horváth

2026. 01. 08.



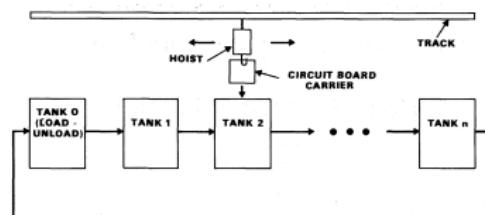
Introduction

- Problem description

- Typical application: electroplating lines
- Hoists move carriers from tank to tank
- Carriers are soaked in the tanks
- Soaking times must be held within prescribed limits

- Cyclic-HSP (CHSP)

- Carriers are moved between tanks by preprogrammed hoists
- After each cycle the same system state is reached
- Introduction of a new carrier into the system → new cycle
- Objective: maximize the throughput of the system



Single-hoist CHSP setup

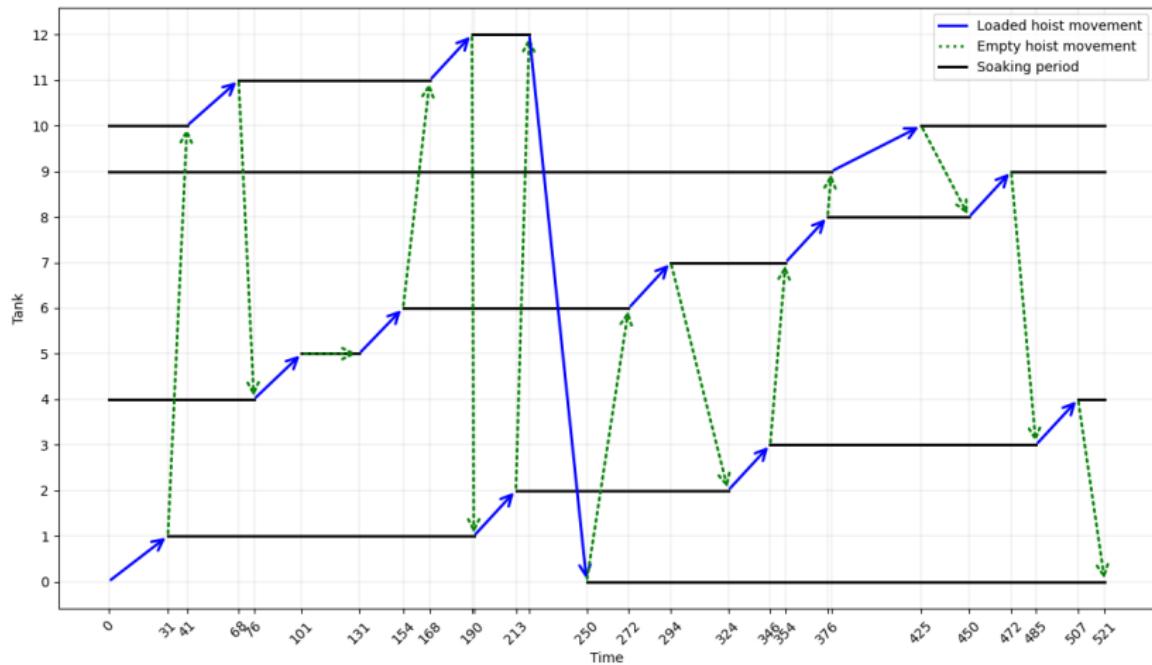


Solution method - MIP formulation

- Want to find the optimal removal time for each tank
- Constraints ensure:
 - no two carriers occupy the same tank at any time
 - no two moves are done simultaneously
 - the hoist has enough time to travel
 - soaking times are within the given boundaries
- Calculate entry times



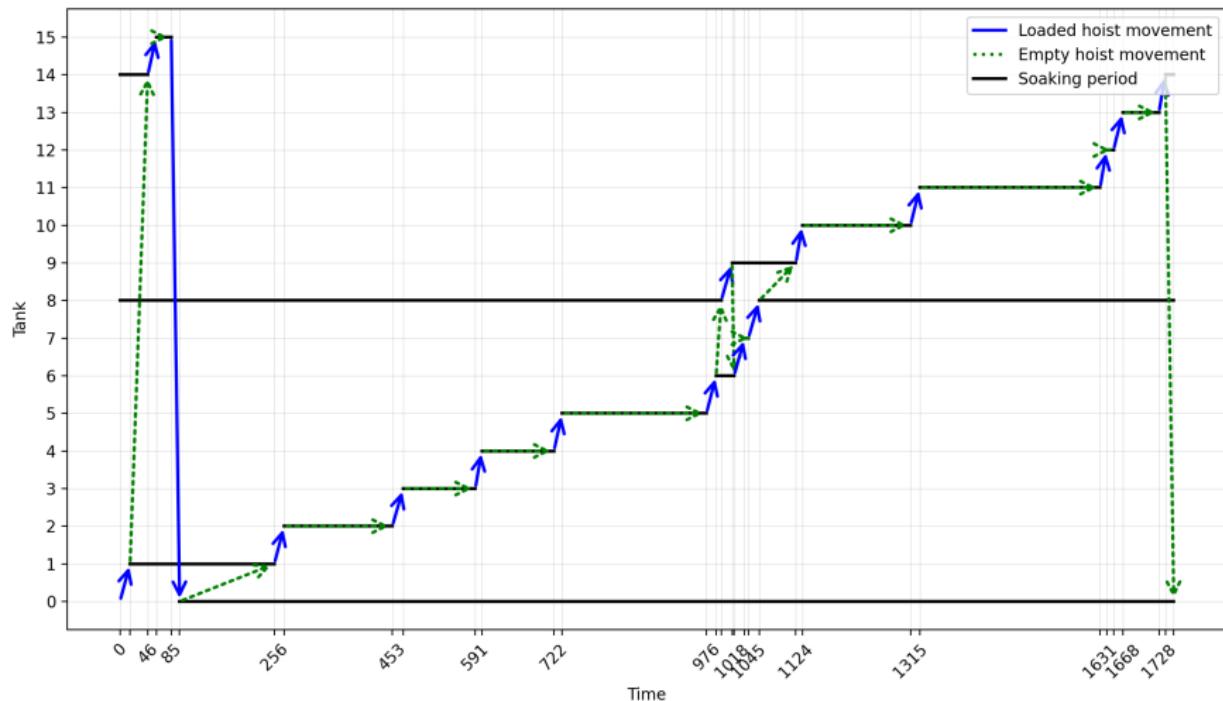
Implementation and examples



solution of 12 tanks example



Implementation and examples



solution of 15 tanks example



Directions for further study

- Single-hoist case
 - multi-purpose tanks
 - duplicated tanks
- Multi-hoist case
 - multiple-hoist on a single line
 - collisions must be avoided



References

- Phillips, L. W., and P. S. Unger. "Mathematical Programming Solution of a Hoist Scheduling Program." *A I I E Transactions* 8 (2): 219–25. (1976).
- Emna Laajili. Modélisation et algorithmes pour le dimensionnement et l'ordonnancement cyclique d'atelier de traitement de surface. Automatique / Robotique. Université Bourgogne Franche-Comté, (2021).
- Manier, Marie-Ange, and Christelle Bloch. "A classification for hoist scheduling problems." *International Journal of Flexible Manufacturing Systems* 15.1: 37-55. (2003).



Thank you for your kind attention!

