

# Resampling Based Estimation of Generative Models

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# Motivation

## Generative models

Models that create i.i.d. samples from a distribution given some initial parameters:

- ▶ Diffusion models, ChatGPT
- ▶ Inverse cumulative distribution functions
- ▶ ARIMA models (for multiple trajectories)
- ▶ Scientific experiments

## The Goal:

Given an original sample  $S^{(0)}$ , estimate the “parameters” that could have generated it.

# Motivation

## Standard methods for parameter estimation

- ▶ Maximum likelihood estimation
- ▶ Stochastic gradient descent
- ▶ Assumes knowledge about the model structure
- ▶ Provides only point estimates
- ▶ Asymptotic guarantees for confidence regions

## Why bother?

- ▶ What if the data is generated from a black box?  
Instead: Distribution-free methods
- ▶ Different point estimates could lead to different interpretations (Rashomon-effect)  
Instead: Confidence regions
- ▶ Asymptotic guarantees don't work well for small sample sizes  
Instead: Exact guarantees for finite samples

## Assumptions

- ▶ There exists a “parameter” space  $\Theta$  containing  $\theta^*$ , that parametrizes the distribution from which the original sample  $S^{(0)}$  is obtained from
- ▶ Instead of assuming the parametrization of the data generation process (e.g., knowing the likelihood function)
- ▶ There is a black box, that can generate i.i.d. samples  $S_\theta^{(1)}, \dots, S_\theta^{(m)}$  from  $\mathbb{P}_\theta$  given any parameter  $\theta$ .
- ▶ The seed for the black box can be fixed.

# Estimating confidence regions

## The Resampling framework

- ▶ Given a parameter  $\theta$
- ▶ 1. Generate  $m - 1$  alternative samples from  $\mathbb{P}_\theta$
- ▶ 2. Assign a real number to each sample based on  $\theta$  called its **reference variable**:  $Z_\theta^{(i)} := T(S_\theta^{(i)}, \theta)$
- ▶ 3. Rank the samples based on the reference variables, and denote the **rank** of the original sample with

$$\mathcal{R}_\theta^{(m)} = 1 + \sum_{i=1}^{m-1} \mathbb{I}_{\{Z_\theta^{(i)} < Z_\theta^{(0)}\}}$$

## Theorem (Csáji and Tamás, 2019)

$\mathbb{P}(\theta^* \in \{\theta \in \Theta \mid p \leq \mathcal{R}_\theta^{(m)} \leq q\}) = \frac{q-p+1}{m}$  if there is almost surely a strict ordering of the reference variables

# Reference variables

Reference variable  $Z_\theta^{(i)} := T(S_\theta^{(i)}, \theta)$  depends on  $\theta$  explicitly;  
e.g., Maximum Likelihood based reference variable:

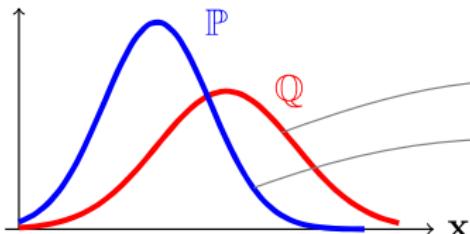
$$Z_\theta^{(i)} = \|\nabla_\theta \mathcal{L}(\theta, S_\theta^{(i)})\|^2$$

Introducing a seed component  $Z_\theta^{(i)} := T(S_\theta^{(i)}, \theta, \xi_i)$ ;  
e.g., MMD-based reference variable:

$$Z_\theta^{(i)} = \widehat{\text{MMD}}^2[S_\theta^{(i)}, S_{\theta, \xi_i}^{(i+m)}]$$

Where  $\widehat{\text{MMD}}^2$  is an unbiased for the Maximum Mean Discrepancy

$p(x)$

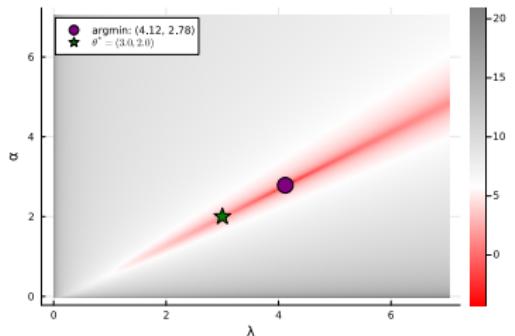


Reproducing Kernel Hilbert Space

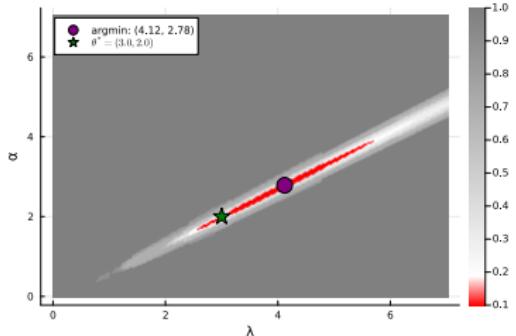
RKHS embedding of  $\mathbb{Q}$

RKHS embedding of  $\mathbb{P}$

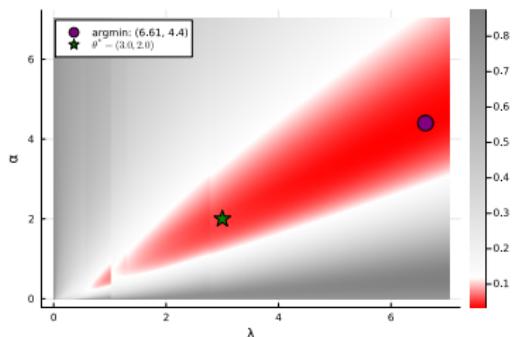
# Examples for confidence regions (Gamma distribution)



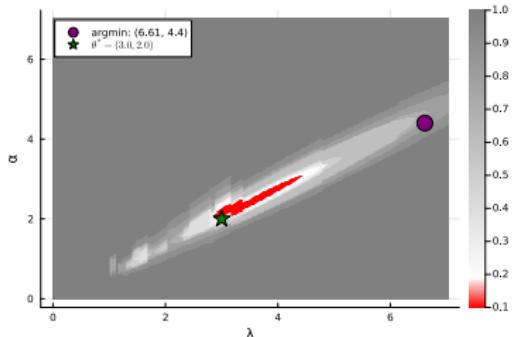
(a) ML reference variable



(b) ML Rank



(c) MMD reference variable



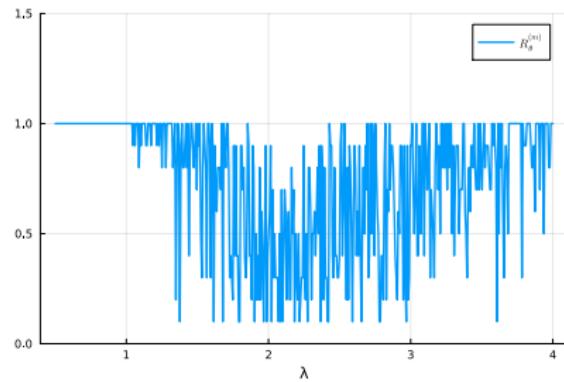
(d) MMD Rank

# Point estimation: The smoothed rank

Idea:

$$\hat{\theta} \in \operatorname{argmin}_{\theta \in \Theta} \mathcal{R}_{\theta}^{(m)}$$

Problem:



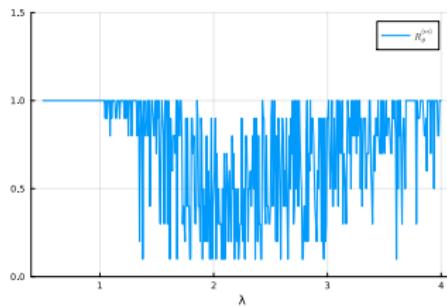
(a) Not fixing the seed

# Point estimation: The smoothed rank

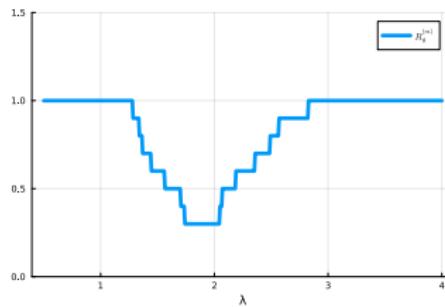
Idea:

$$\hat{\theta} \in \operatorname{argmin}_{\theta \in \Theta} \mathcal{R}_{\theta}^{(m)}$$

Problem:



(a) Not fixing the seed



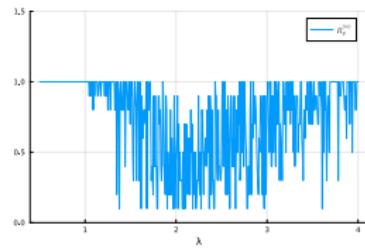
(b) Fixing the seed

# Point estimation: The smoothed rank

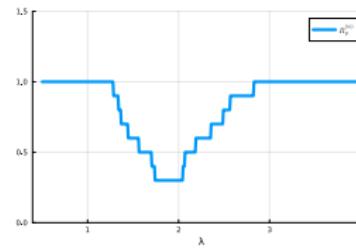
Idea:

$$\hat{\theta} \in \operatorname{argmin}_{\theta \in \Theta} \mathcal{R}_{\theta}^{(m)}$$

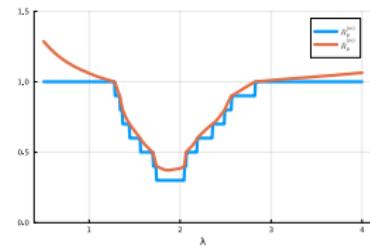
Solution:



(a) Not fixing the seed



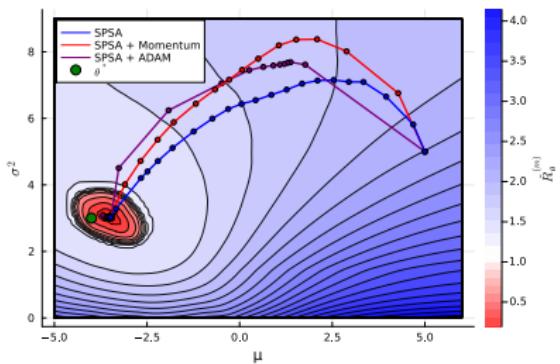
(b) Fixing the seed



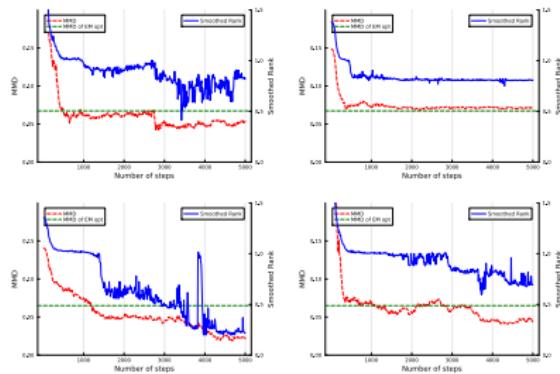
(c) Smoothed rank

# Optimization

## Stochastic optimization of the smoothed rank (SPSA)



(a) Gaussian distribution



(a) Gaussian Mixture Model

# Asymptotic properties in the number of resamplings

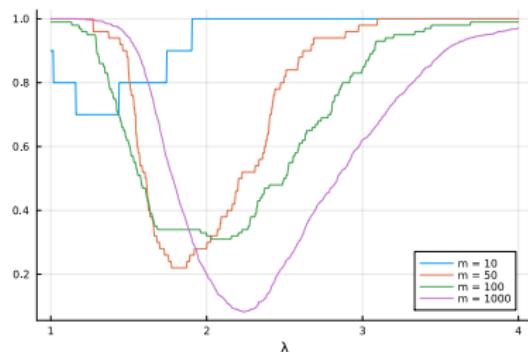
## Definition

The normalised rank can be defined as

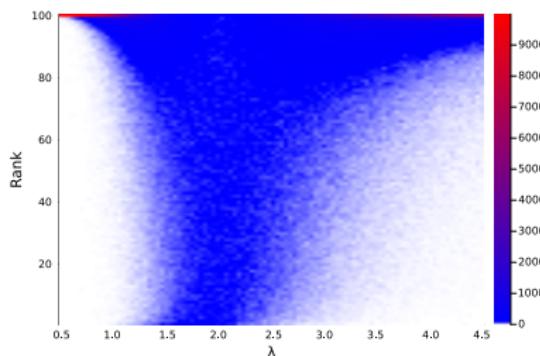
$$\mathcal{R}_\theta^{(m)} = \frac{1}{m} \left( 1 + \sum_{i=1}^{m-1} \mathbb{I}_{\{Z_\theta^{(i)} < Z_\theta^{(0)}\}} \right)$$

## Proposition

$\lim_{m \rightarrow \infty} \mathcal{R}_\theta^{(m)} = F_{Z_\theta}(Z_\theta^{(0)})$  where  $F_{Z_\theta}$  denotes the CDF of  $Z_\theta^{(i)}$



(a) Increasing the n.o. resamplings



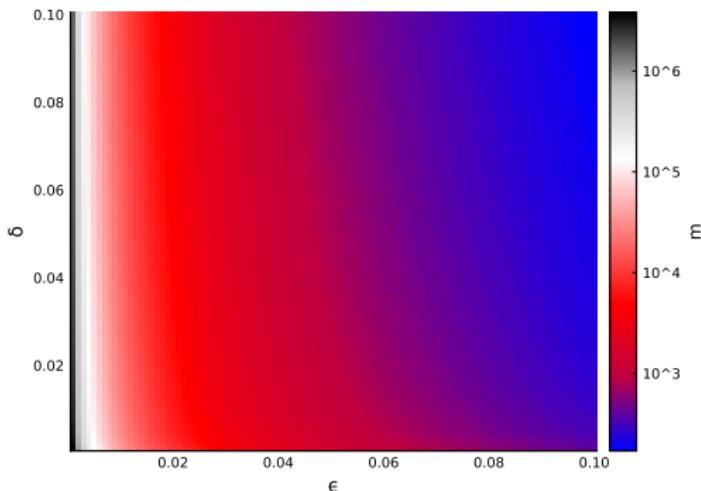
(b) Distribution of Rank

# Convergence rate

## Proposition

A finite sample bound based on the concentration inequality of Dvoretzky-Kiefer-Wolfowitz (quantitative Glivenko-Cantelli):

$$\mathbb{P} \left( \left| \mathcal{R}_{\theta}^{(m)} - F_{Z_{\theta}} \left( Z_{\theta}^{(0)} \right) \right| > \varepsilon \right) \leq 2 \exp \left( -2m\varepsilon^2 + 4\varepsilon \right)$$



# Uniform convergence

## Question:

Is it possible to guarantee a uniform convergence over  $\Theta$ ?

## Definition (Alon et al., 1997)

A set of  $\mathcal{X} \rightarrow \mathbb{R}$  functions  $\mathcal{H}$  is **Uniform Glivenko-Cantelli (UGC)** if for every  $\varepsilon > 0$  it holds that

$$\lim_{I \rightarrow \infty} \sup_{\mu \in M_{\mathcal{X}}} \mathbb{P} \left( \sup_{m \geq I} \sup_{f \in \mathcal{H}} \left| \frac{1}{m} \sum_{i=1}^m f(x_i) - \int_{\mathcal{X}} f(x) d\mu \right| \geq \varepsilon \right) = 0$$

where  $\{x_i\}$  are sampled i.i.d. from the distribution  $\mu$ .

## Theorem (Alon et al., 1997)

Let  $\mathcal{H}$  be a set of  $\mathcal{X} \rightarrow [0, 1]$  functions. Then  $\mathcal{H}$  is UGC if and only if the  $V_{\gamma}$ -dimension of  $\mathcal{H}$  is finite for every  $\gamma > 0$

# Uniform convergence

## Theorem

Let  $S^{(0)}$  be a fixed original sample. If there exists a set of  $\Theta \rightarrow \mathbb{R}$  functions  $\mathcal{G}$  such that  $Z_{\theta, \xi}^{(0)} \in \mathcal{G}$  for every  $\xi \in \mathcal{Q}$ , and  $P\dim(\mathcal{G}) < \infty$ , then

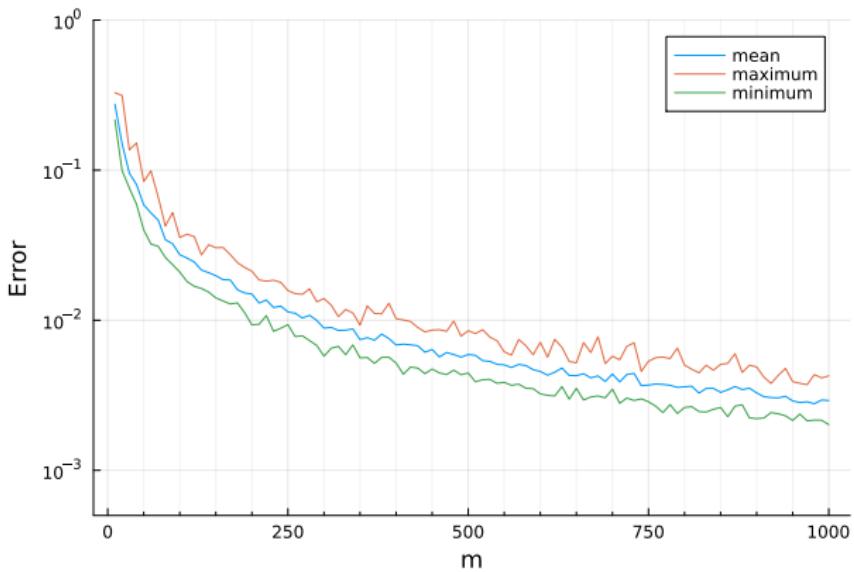
$$\lim_{I \rightarrow \infty} \sup_{\theta \in \Theta} \mathbb{P} \left( \sup_{m \geq I} \sup_{\xi \in \mathcal{Q}} \left| \mathcal{R}_{\theta, \xi}^{(m)} - F_{Z_{\theta}^{(1)}}(Z_{\theta, \xi}^{(0)}) \right| \geq \varepsilon \mid S^{(0)} \right) = 0$$

## Examples

- ▶ Non-randomized reference variables
- ▶ ML-based reference variable from the exponential distribution family (across the sample space)
- ▶ MMD-based reference variable using a finite dimensional RKHS and a fixed seed (across the sample space)

# Uniform convergence

Uniform convergence for ML-based reference variables, in a single parameter exponential family, across the sample space



# Uniform convergence

Some useful tools to prove finite pseudo-dimension

**Theorem (Anthony and Bartlett, 1999)**

If  $\mathcal{H}$  is a vector space of  $\mathcal{X} \rightarrow \mathbb{R}$  functions, then

$$\text{Pdim}(\mathcal{H}) = \dim(\mathcal{H})$$

**Lemma (Anthony and Bartlett, 1999)**

If  $g : \mathbb{R} \rightarrow \mathbb{R}$  is a non-decreasing function, then for

$\mathcal{G} = \{g(f(x)) | f \in \mathcal{H}\}$  it holds that  $\text{Pdim}(\mathcal{G}) \leq \text{Pdim}(\mathcal{H})$

## Lemma

*Let  $g$  be any  $\Psi \rightarrow \mathcal{X}$  function. Then for  $\mathcal{G} = \{h(g(\psi)) | h \in \mathcal{H}\}$  it holds that  $\text{Pdim}(\mathcal{G}) \leq \text{Pdim}(\mathcal{H})$ .*

# Asymptotic behaviour in sample size

Assumption:  $S^{(0)} = (x_1, \dots, x_n)$  contains i.i.d. instances from  $\mathbb{P}_\theta$ .

## Definition

A reference variable is *consistent*, if it holds that

$$\lim_{n \rightarrow \infty} Z_\theta^{(i)} = \begin{cases} 0 & \text{if } x_j \sim \mathbb{P}_\theta \text{ i.i.d.} \\ c \in \mathbb{R}_+ \cup \{\infty\} & \text{else} \end{cases}$$

almost surely for any  $\theta \in \Theta$  parameter and  $i = 0, \dots, m-1$ .

## Proposition

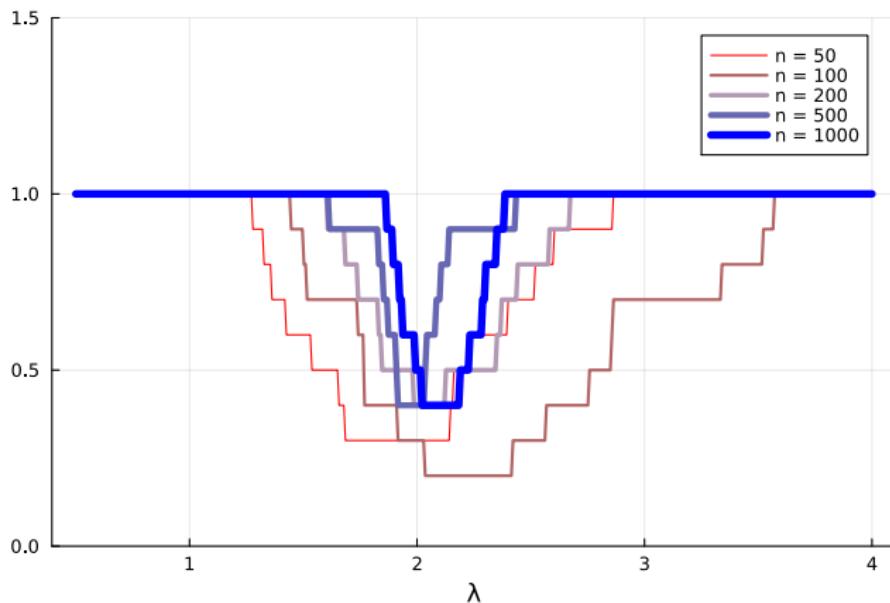
If  $\{Z_\theta^{(i)}\}$  are *consistent*, then the normalised rank  $\mathcal{R}_\theta^{(m)}$  constructed from it has the following properties:

- ▶ I.)  $\mathcal{R}_\theta^{(m)} \rightarrow 1$  a.s. as  $n \rightarrow \infty$  if  $\mathbb{P}_{\theta^*} \neq \mathbb{P}_\theta$ .
- ▶ II.)  $\mathcal{R}_\theta^{(m)} \xrightarrow{d} U_m[0, 1]$  as  $n \rightarrow \infty$  if  $\mathbb{P}_{\theta^*} = \mathbb{P}_\theta$  where  $U_m[0, 1]$  is the discrete uniform distribution over  $\left\{ \frac{1}{m}, \dots, \frac{m-1}{m}, 1 \right\}$ .

# Asymptotic behaviour in sample size

## Proposition

MMD-based reference variables using *characteristic kernels* are *consistent* (e.g., Gaussian, Laplace kernels)



# Conclusions

## Conclusions

Benefits of the proposed framework:

- ▶ Exact confidence regions for finite samples
- ▶ Distribution free
- ▶ Point estimates
- ▶ Asymptotic guarantees

## Future directions

- ▶ Rashomon sets
- ▶ Fine-tuning diffusion models

# AI Declaration

Throughout this project, AI tools (in this case ChatGPT) were used for the following purposes:

- ▶ To assist with writing the code for the simulations and for creating the figures containing the results of the simulations.
- ▶ To find the original sources of some theorems that were borrowed from textbooks.

# References

-  Alon, Noga et al. (1997). "Scale-sensitive dimensions, uniform convergence, and learnability". In: *Journal of the ACM (JACM)* 44.4, pp. 615–631.
-  Anthony, Martin and Peter L. Bartlett (1999). *Neural Network Learning: Theoretical Foundations*. 1st. Cambridge University Press. ISBN: 052111862X.
-  Csáji, Balázs Csanád and Ambrus Tamás (2019). "Semi-Parametric Uncertainty Bounds for Binary Classification". In: *2019 IEEE 58th Conference on Decision and Control (CDC)*, pp. 4427–4432. DOI: 10.1109/CDC40024.2019.9029477.